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Be Everywhere - Hear Everything (BEE)

Audio reconstruction with **dynamic emitters** at **arbitrary listener locations**, leveraging inputs from **sparse A/V receivers**.



Input:

N A/V sensor captures
(e.g. N=4)

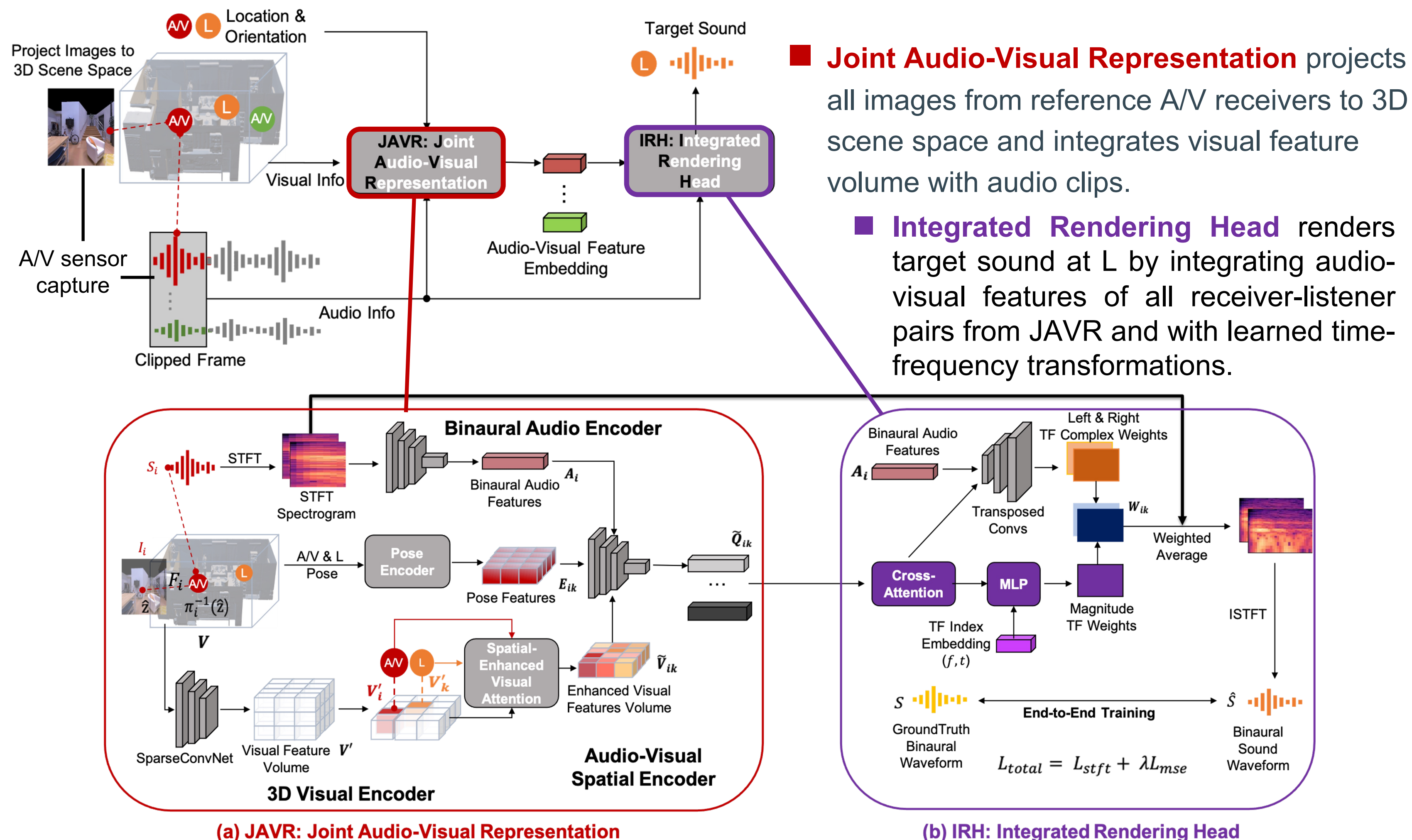
Output:

Spatial audio waveform
heard at Listener 1

✔ No requirement of given/set emitters' locations

✔ No requirement of specific emitters' waveform

BEE Components



■ **Joint Audio-Visual Representation** projects all images from reference A/V receivers to 3D scene space and integrates visual feature volume with audio clips.

■ **Integrated Rendering Head** renders target sound at L by integrating audio-visual features of all receiver-listener pairs from JAVR and with learned time-frequency transformations.

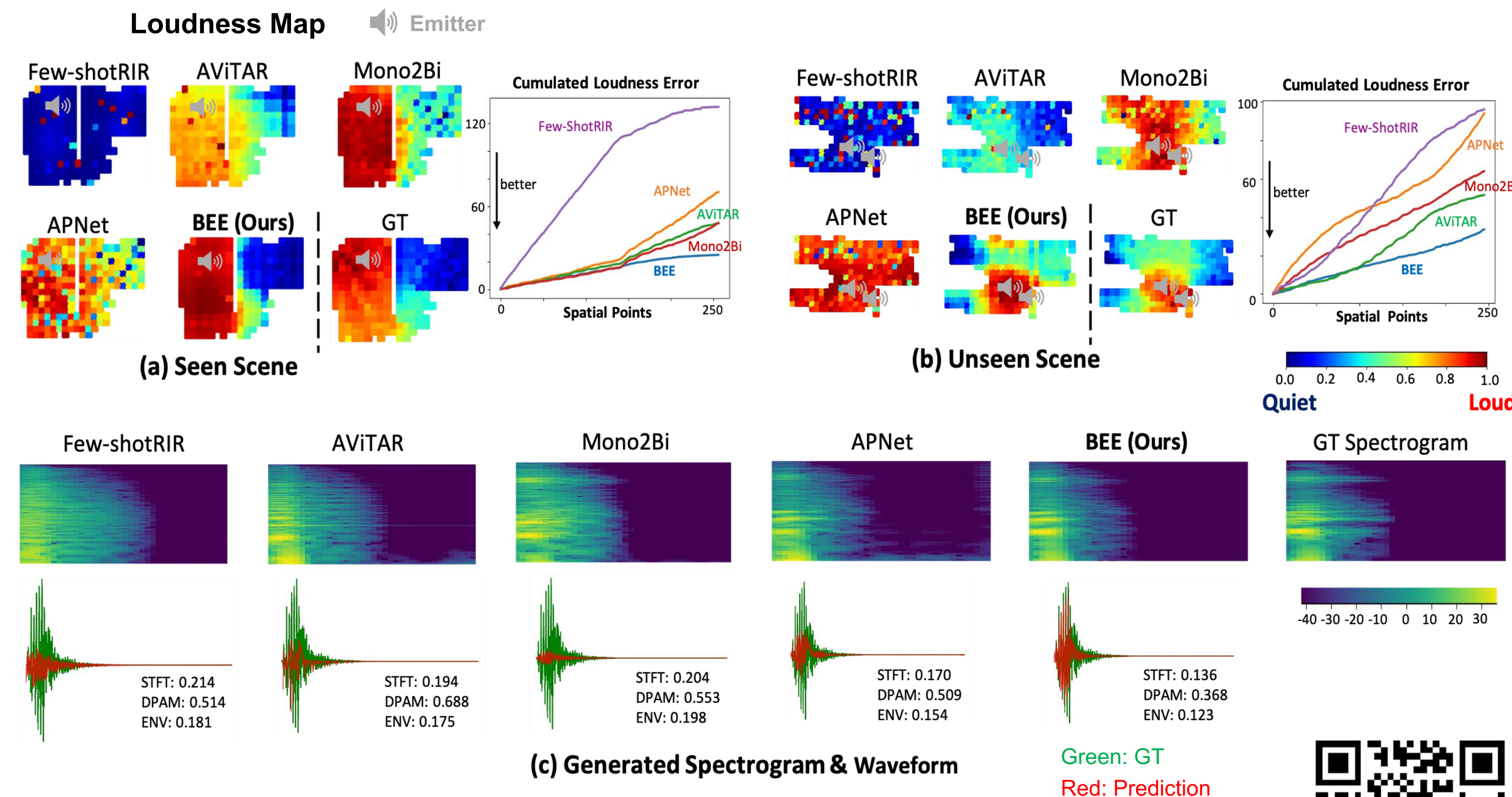
Evaluations & Results

Method	Visual	Transform	Seen Scenes			Unseen Scenes		
			STFT ↓	DPAM ↓	ENV ↓	STFT ↓	DPAM ↓	ENV ↓
<i>Replica</i> : 12 seen scenes, 6 unseen scenes								
Nearest	✗	✓	1.614	0.992	0.257	1.686	0.993	0.277
Mean	✗	✓	1.600	1.039	0.265	1.618	1.036	0.275
Interpolation	✗	✓	1.575	1.039	0.256	1.614	1.033	0.267
AViTAR [6]	✓	✗	0.181	0.334	0.163	0.199	0.327	0.184
Few-shotRIR [17]	✓	✗	0.233	0.449	0.227	0.245	0.436	0.239
Mono2Binaural [10]	✓	✓	0.194	0.376	0.156	0.236	0.364	0.177
APNet [30]	✓	✓	0.164	0.263	0.154	0.185	0.253	0.176
BEE (Ours)	✓	✓	0.151	0.215	0.133	0.177	0.221	0.160
<i>Matterport3D</i> : 54 seen scenes, 25 unseen scenes								
Nearest	✗	✓	4.851	1.047	0.837	5.029	1.064	0.874
Mean	✗	✓	3.174	1.068	0.611	3.456	1.078	0.650
Interpolation	✗	✓	3.475	1.066	0.658	3.521	1.081	0.669
AViTAR [6]	✓	✗	0.516	0.610	0.595	0.509	0.625	0.548
Few-shotRIR [17]	✓	✗	0.597	0.476	0.731	0.591	0.500	0.694
Mono2Binaural [10]	✓	✓	0.533	0.440	0.545	0.582	0.492	0.529
APNet [30]	✓	✓	0.500	0.352	0.537	0.515	0.393	0.528
BEE (Ours)	✓	✓	0.425	0.274	0.455	0.438	0.348	0.458
Components	3D Vis Enc	JAVR	IRH	Total	Methods	Mono2Binaural [10]	APNet [30]	BEE (Ours)
Speed (ms/sample)	16.00	18.40	11.94	30.34	Votes	29.6%	26.4%	44%

✔ SOTA Accuracy & Quality of Spatial Sound Reconstruction

✔ Generalization Ability for Unseen Scenes

✔ Real-time Inference Speed



Visit our demo video to see and listen to examples!

